

Sensitivity Analysis of Air Pollution Models

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Outline

- Introduction
- Mathematical background
- Numerical experiments
- Concluding remarks

Introduction

- Goal

The aim is to propose a new mechanism for sensitivity studies of the concentrations levels of some important pollutants (like ozone O_3) in real-live scenarios of air pollution transport over Europe with Unified Danish Eulerian Model (UNI-DEM).

- Sensitivity analysis studies

- Motivation

Mathematical Background

- Unified Danish Eulerian Model (UNI-DEM)
- Total Sensitivity Indices
- Sobol' Approach for Computing Global Sensitivity Indices

Mathematical Background: UNI-DEM

$$\begin{aligned} \frac{\partial c_s}{\partial t} = & \frac{\partial(uc_s)}{\partial x} - \frac{\partial(vc_s)}{\partial y} - \frac{\partial(wc_s)}{\partial z} + \\ & + \frac{\partial}{\partial x} \left(K_x \frac{\partial(c_s)}{\partial x} \right) + \frac{\partial}{\partial y} \left(K_y \frac{\partial(c_s)}{\partial y} \right) + \frac{\partial}{\partial z} \left(K_z \frac{\partial(c_s)}{\partial z} \right) + \\ & + E_s + Q_s(c_1, c_2, \dots, c_q) - (k_{1s}k_{2s}c_s), \quad s = 1, 2, \dots, q. \end{aligned}$$

q

- number of equations = number of chemical species,

c_s

- concentrations of the chemical species,

u, v, w

- components of the wind along the coordinate axes,

K_x, K_y, K_z

- diffusion coefficients,

E_s

- emissions in the space domain,

k_{1s}, k_{2s}

- coefficients of dry and wet deposition respectively ($s = 1, \dots, q$),

$Q_s(c_1, c_2, \dots, c_q)$

- non-linear functions that describe

the chemical reactions between species.

Mathematical Background: Mathematical Model

- The mathematical model

$$u = f(\mathbf{x}), \quad \text{where } \mathbf{x} = (x_1, x_2, \dots, x_d) \in U^d \equiv [0, 1]^d$$

is a vector of input parameters with a joint p.d.f. $p(\mathbf{x}) = p(x_1, \dots, x_d)$.

- Local sensitivity: $\mathbf{x} = \mathbf{x}^* \in U^d, \quad u^* = f(\mathbf{x}^*)$.
- Global sensitivity: $u = f(\mathbf{x}), \quad \mathbf{x} \in U^d$.

Mathematical Background: Total Sensitivity Index

- Total Sensitivity Index of input parameter x_i , $i \in \{1, \dots, d\}$:

$$S_{x_i}^{tot} = S_i + \sum_{l_1 \neq i} S_{il_1} + \sum_{l_1, l_2 \neq i, l_1 < l_2} S_{il_1 l_2} + \dots + S_{il_1 \dots l_{d-1}},$$

where

$S_{il_1 \dots l_{j-1}}$ – j^{th} order sensitivity index for parameter x_i ($1 \leq j \leq d$),

$j = 1$: S_i – "the main effect" of x_i .

- Classification of input parameters:

–very important:	0.8	<	$S_{x_i}^{tot}$	<	0.8
–important:	0.5	<	$S_{x_i}^{tot}$	<	0.5
–unimportant:	0.3	<	$S_{x_i}^{tot}$	<	0.3
–irrelevant:			$S_{x_i}^{tot}$	<	0.3

Mathematical Background: Sobol' Approach

ANalysis Of VAriances (ANOVA) HDMR of a square integrable function $f(\mathbf{x})$:

$$f(\mathbf{x}) = f_0 + \sum_{s=1}^d \sum_{l_1 < \dots < l_s} f_{l_1 \dots l_s}(x_{l_1}, x_{l_2}, \dots, x_{l_s}),$$

where

- f_0 - constant,
- $\int_0^1 f_{l_1 \dots l_s}(x_{l_1}, x_{l_2}, \dots, x_{l_s}) dx_{l_k} = 0, \quad 1 \leq k \leq s, \quad s = 1, \dots, d.$

I.M. Sobol, Multidimensional Quadrature Formulas and Haar Functions, Nauka, Moscow, 1969.

I.M. Sobol, Sensitivity estimates for nonlinear mathematical models, Mathematical Modelling and Computational Experiments, 1(4) (1993) 407–414.

Mathematical Background: Sobol' Approach

Therefore

- $\int_{U^d} f_{i_1, \dots, i_s} f_{j_1, \dots, j_l} \, d\mathbf{x} = 0, \quad (i_1, \dots, i_s) \neq (j_1, \dots, j_l), \quad s, l \in \{1, \dots, d\}$

and the functions in the right-hand side are defined in a unique way:

- $f_0 = \int_{U^d} f(\mathbf{x}) \, d\mathbf{x}$

- $f_{l_1}(x_{l_1}) = \int_{U^{d-1}} f(\mathbf{x}) \prod_{k \neq l_1} d\mathbf{x}_k - f_0, \quad l_1 \in \{1, 2, \dots, d\}$

- $f_{l_1 l_2}(x_{l_1}, x_{l_2}) = \int_{U^{d-2}} f(\mathbf{x}) \prod_{k \neq l_1, l_2} d\mathbf{x}_k - f_0 - f_{l_1}(x_{l_1}) - f_{l_2}(x_{l_2}),$
 $l_1, l_2 \in \{1, 2, \dots, d\}$

Mathematical Background: Global (Sobol') Sensitivity Indices

Definition (Sobol'):

$$S_{l_1 \dots l_s} = \frac{\mathbf{D}_{l_1 \dots l_s}}{\mathbf{D}}, \quad s \in \{1, \dots, d\},$$

where

- variances $\mathbf{D}_{l_1 \dots l_s} = \int f_{l_1 \dots l_s}^2 dx_{l_1} \dots dx_{l_s}$,
- total variance $\mathbf{D} = \int_{U^d} f^2(\mathbf{x}) d\mathbf{x} - f_0^2$,

and the following properties hold:

- $S_{l_1 \dots l_s} \geq 0$, $\sum_{s=1}^d \sum_{l_1 < \dots < l_s} S_{l_1 \dots l_s} = 1$.

Methods for Evaluating Global Sensitivity Indices

Method	Cost (Model runs)	Sensitivities
FAST (1973)	$O(d^2)$	$S_i, \forall i$
Sobol (1993)	$N(2d + 2)$	$S_i, S_{x_i}^{tot}, \forall i$
EFAST (1999)	dN	$S_i, S_{x_i}^{tot}, \forall i$
Saltelli (2002)	$N(d + 2)$	$S_i, \forall i, S_{lj}, \forall l, j, l \neq i$

Mathematical Background: Sobol' Monte Carlo Algorithm

Let $\mathbf{x} = (\mathbf{y}, \mathbf{z}) \in \mathbb{R}^d$, $\mathbf{y} = (x_{k_1}, x_{k_2}, \dots, x_{k_m}) \in \mathbb{R}^m$, $K = (k_1, k_2, \dots, k_m)$.

Variance of the subset \mathbf{y} :
$$\mathbf{D}_{\mathbf{y}} = \sum_{s=1}^m \sum_{(k_1, \dots, k_m) \in K} \mathbf{D}_{l_1 \dots l_s}.$$

Theorem (Sobol').
$$\mathbf{D}_{\mathbf{y}} = \int f(\mathbf{x}) f(\mathbf{y}, \mathbf{z}') d\mathbf{x} d\mathbf{z}' - f_0^2 \quad \left(f_0 = \int_{U^d} f(\mathbf{x}) d\mathbf{x} \right).$$

Monte Carlo algorithm:

$$\begin{aligned} \frac{1}{N} \sum_{j=1}^N f(\xi_j) &\xrightarrow{P} f_0 & \frac{1}{N} \sum_{j=1}^N f^2(\xi_j) &\xrightarrow{P} \mathbf{D} + f_0^2 \\ \frac{1}{N} \sum_{j=1}^N f(\xi_j) f(\eta_j, \zeta'_j) &\xrightarrow{P} \mathbf{D}_{\mathbf{y}} + f_0^2, & \xi &= (\eta, \zeta). \end{aligned}$$

$$S_{l_1} = S_{(l_1)} = \frac{\mathbf{D}_{(l_1)}}{\mathbf{D}}, \quad S_{(l_1 l_2)} = S_{l_1} + S_{l_2} + S_{l_1 l_2} = \frac{\mathbf{D}_{(l_1 l_2)}}{\mathbf{D}} \implies S_{l_1 l_2}.$$

Approaches for Small Indices: Reducing the Mean Value (I.M. Sobol', 1990)

Motivation: If $\mathbf{D}_y \ll f_0^2 \Rightarrow$ a loss of accuracy.

Approach concept: Choose $c \sim f_0$ and set the function $\varphi(\mathbf{x}) = f(\mathbf{x}) - c$.

Therefore

$$\mathbf{D}_y = \int \varphi(\mathbf{x}) \varphi(\mathbf{y}, \mathbf{z}') d\mathbf{x} d\mathbf{z}' - \omega^2, \quad \text{where } \omega = \int \varphi(\mathbf{x}) d\mathbf{x},$$

$$\mathbf{D} = \int \varphi^2(\mathbf{x}) d\mathbf{x} - \omega^2, \quad \omega = f_0 - c.$$

Variance (standard error) of the estimate:

$$V^{(1)} = V_0^{(1)} + \mathbf{O}(|\omega|), \quad V^{(1)} = \int \varphi^2(\mathbf{x}) \varphi^2(\mathbf{y}, \mathbf{z}') d\mathbf{x} d\mathbf{z}' - (\mathbf{D}_y + \omega^2)^2, \quad \text{where}$$

$$V_0^{(1)} = \int h^2(\mathbf{x}) h^2(\mathbf{y}, \mathbf{z}') d\mathbf{x} d\mathbf{z}' - \mathbf{D}_y^2, \quad h(\mathbf{x}) = f(\mathbf{x}) - f_0.$$

Approaches for Small Indices: A Combined Approach (Saltelli, 2002, Kucherenko, 2007)

- **Approach concept**

- Choose a constant $c \sim f_0$ and set the function $\varphi(\mathbf{x}) = f(\mathbf{x}) - c$.
- Use $\varphi(\mathbf{x})$ rather than $f(\mathbf{x})$:

$$\mathbf{D}_y = \int \varphi(\mathbf{x}) [\varphi(\mathbf{y}, \mathbf{z}') dx dz' - \varphi(\mathbf{x}')] dx dx',$$

$$\mathbf{D} = \int \varphi(\mathbf{x}) [\varphi(\mathbf{x}) - \varphi(\mathbf{x}')] dx dx'.$$

- **Variance of the estimate**

$$V^{(2)} = V_0^{(2)} + \mathbf{O}(|\omega|), \quad V_0^{(2)} = \int h^2(\mathbf{x}) [h(\mathbf{y}, \mathbf{z}') - h(\mathbf{x}')]^2 dx dx' - \mathbf{D}_y^2.$$

Comparison of estimators variances: $V_0^{(2)}$ versus $V_0^{(1)}$

ANOVA-like decomposition of the model function:

$$f(\mathbf{x}) = f_0 + g_1(\mathbf{y}) + g_2(\mathbf{z}) + g_{12}(\mathbf{x}), \quad \text{where}$$

$$g_1(\mathbf{y}) = \int f(\mathbf{x})d\mathbf{z} - f_0, \quad g_2(\mathbf{z}) = \int f(\mathbf{x})d\mathbf{y} - f_0,$$

$$g_{12}(\mathbf{x}) = f(\mathbf{x}) - \int f(\mathbf{x})d\mathbf{y} - \int f(\mathbf{x})d\mathbf{z} + f_0.$$

Proposition (Sobol', Myshetskaya, 2007):

Denote $\delta = \sup |v(\mathbf{y})| \frac{2}{\mathbf{D}_z}$. If $\delta < 1$ and $S_z > \frac{1}{2 - \delta}$, then $V_0^{(2)} < V_0^{(1)}$,

where $v(\mathbf{y}) = \int g_2(\mathbf{z}') g_{12}(\mathbf{y}, \mathbf{z}')d\mathbf{z}'$.

Numerical Results from the Preliminary Stage

The input data:

$$r_s(\alpha) = \frac{c_s^\alpha(a_s^{imax}, b_s^{jmax})}{c_s^{max}}, \quad \text{where } \alpha_i \in \{0.1, 0.2, \dots, 2.0\}, \quad \alpha = \{\alpha_i\} \quad \text{and}$$

$$i = 1, 2, \dots, 69$$

– the time-dependent chemical reactions,

$$i = 1, 2, \dots, 47$$

– the constant chemical reactions,

$$s = 1, \dots, 35$$

– the chemical species (pollutants),

$$c_s^{max} = c_s^{max}(a_s^{imax}, b_s^{jmax})$$

– the maximum mean value of the concentration of chemical species for July 1998.

Numerical Results from the Preliminary Stage

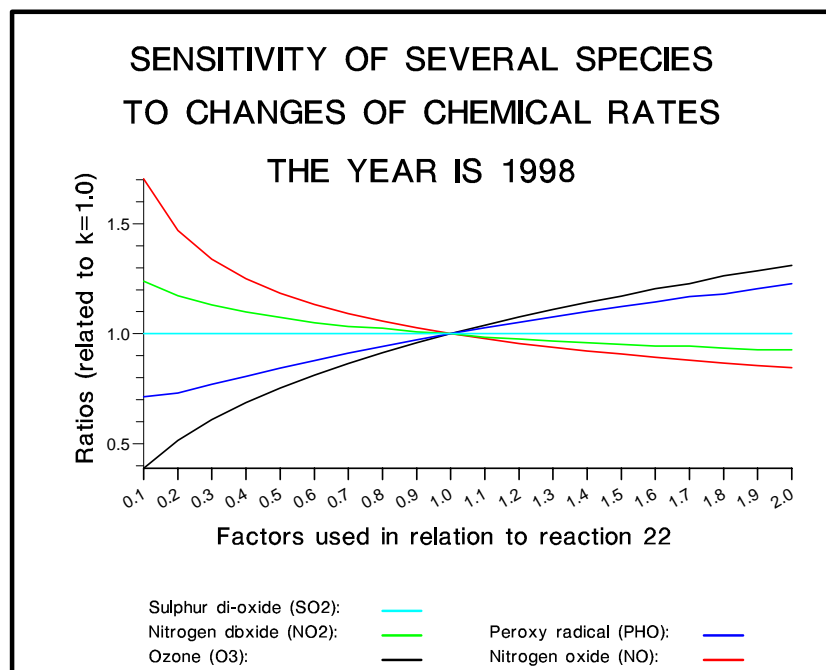


Figure 1: Sensitivity of several species to changes of chemical rates (1998).

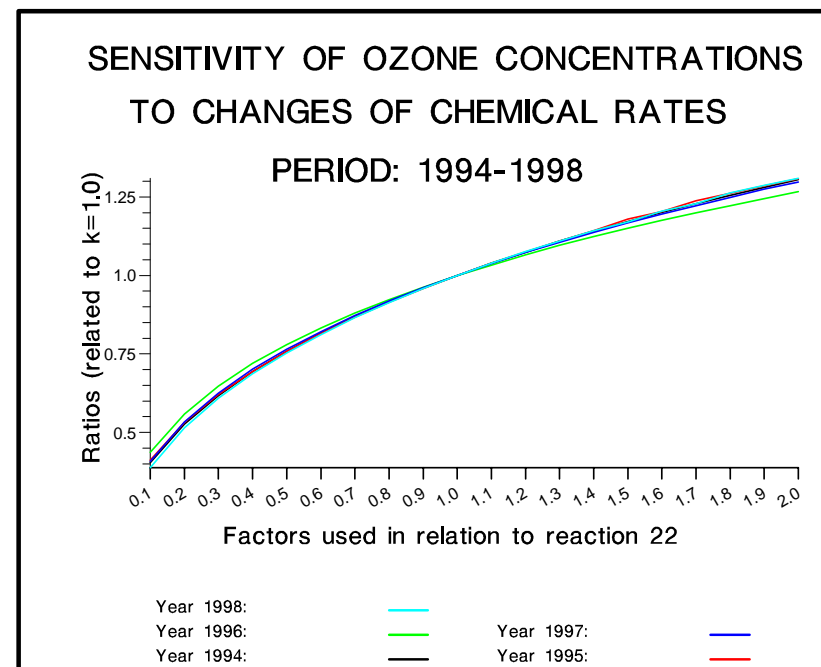


Figure 2: Sensitivity of ozone concentrations to changes of chemical rates (period 1994-1998).

Numerical Results from the Preliminary Stage

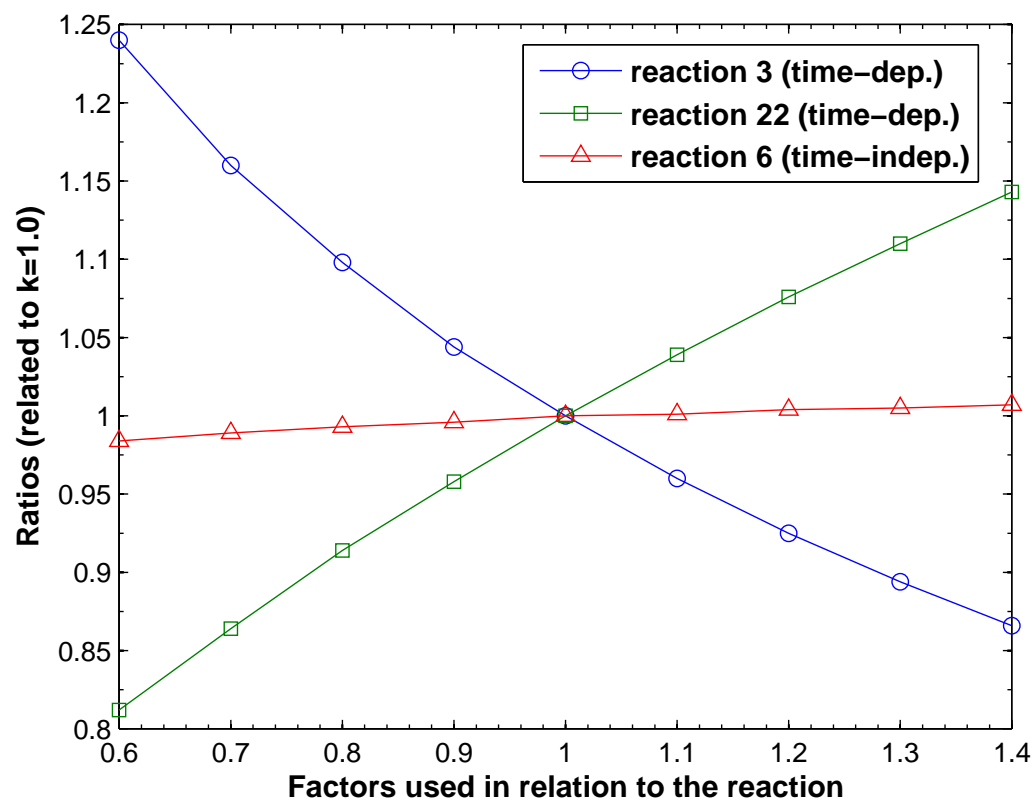


Figure 3: Sensitivity of ozone concentrations to changes of chemical rates (July 1998).

The Case Study: Approximation

Input data: $r_s(\alpha)$, $s \leftrightarrow O_3$, $i = \{3, 22, 6\}$, **Denote** $\mathbf{x} := \alpha$.
 $\alpha_i \in \{0.6, 0.7, \dots, 1.4\}$, $\alpha = (\alpha_3, \alpha_{22}, \alpha_6)$.

Approximation function: $f_s(\mathbf{x}) = \sum_{j=0}^k \sum_{\substack{\nu_1, \nu_2, \dots, \nu_d = 0 \\ \nu_1 + \dots + \nu_d = j}}^k a_{\nu_1 \dots \nu_d} x_1^{\nu_1} x_2^{\nu_2} \dots x_d^{\nu_d}$.

Error estimation: $\|f_s - r_s\|_2^2 = \sum_{l=1}^n [f_s(\mathbf{x}_l) - r_s(\mathbf{x}_l)]^2$, $\mathbf{x}_l \in [0.6; 1.4]^3$.

Table 1: Squared 2-vector norm of the residual (f_s is a polynomial of 4th degree).

$\mathbf{x} \in [0.1; 2.0]^3$	$\mathbf{x} \in [0.6; 1.4]^3$
0.016	0.00005

Numerical Results

Table 2: Total sensitivity indices of input parameters obtained using different variance-based approaches for sensitivity analysis.

approach \ estimated quantity	Standard (Sobol')		Approaches for small indices	
			red. of the m.v.	combined
	$\mathbf{x} \in [0.1; 2.0]^3$	$\mathbf{x} \in [0.6; 1.4]^3$	$\mathbf{x} \in [0.6; 1.4]^3$	$\mathbf{x} \in [0.6; 1.4]^3$
integrand $g(\mathbf{x})$	$f(\mathbf{x})$	$f(\mathbf{x})$	$f(\mathbf{x}) - c$	$f(\mathbf{x}) - c$
c	-	-	0.51737	0.51737
g_0	0.51520	0.51634	0.25145	0.25145
\mathbf{D}	0.26181	0.26446	0.07061	0.00530
S_1	0.26386	0.26530	0.27354	0.52979
S_2	0.26447	0.26359	0.26713	0.46142
S_3	0.25348	0.25209	0.22406	0.00222
$\sum_{i=1}^3 S_i$	0.78182	0.78097	0.76474	0.99342

Numerical Results

Table 3: Total sensitivity indices of input parameters obtained using different variance-based approaches for sensitivity analysis.

approach estimated quantity	Standard (Sobol')		Approaches for small indices	
	$\mathbf{x} \in [0.1; 2.0]^3$	$\mathbf{x} \in [0.6; 1.4]^3$	red. of the m.v.	combined
			$\mathbf{x} \in [0.6; 1.4]^3$	$\mathbf{x} \in [0.6; 1.4]^3$
S_{12}	0.06885	0.06941	0.07994	0.00628
S_{13}	0.06598	0.06634	0.06845	0.00009
S_{23}	0.06613	0.06592	0.06686	0.00021
$\sum_{i,j=1,i<j}^3 S_{ij}$	0.20096	0.20167	0.21525	0.00658
S_{123}	0.01722	0.01736	0.02001	0.000003
$S_{x_1}^{tot}$	0.41592	0.41841	0.44195	0.53615
$S_{x_2}^{tot}$	0.41667	0.41627	0.43395	0.46791
$S_{x_3}^{tot}$	0.40281	0.40170	0.37938	0.00252

Numerical Results

Table 4: First order and total sensitivity indices of input parameters obtained using combined approaches and two approaches implemented in R package.

estimated quantity	$\mathbf{x} \in [0.1; 2.0]^3$			$\mathbf{x} \in [0.6; 1.4]^3$		
	combined approach	R Package		combined approach	R Package	
		Sobol, Saltelli	FAST		Sobol, Saltelli	FAST
S_1	0.48262	0.46645	0.47933	0.52979	0.53029	0.52783
S_2	0.51080	0.54567	0.50928	0.46142	0.47884	0.46034
S_3	0.00104	0.00288	0.00101	0.00222	0.00254	0.00221
$S_{x_1}^{tot}$	0.48807	0.48641	0.48800	0.53615	0.53760	0.53609
$S_{x_2}^{tot}$	0.51592	0.50845	0.51604	0.46791	0.45089	0.46799
$S_{x_3}^{tot}$	0.00157	-0.00043	0.00308	0.00252	0.00180	0.00365

More information about R language and environment for statistical computing: <http://www.r-project.org/>

Conclusion

Some of the most advanced variance-based approaches for sensitivity analysis have been applied to study the influence of chemical rates variation over the concentration levels of air pollutants using UNI-DEM.

- Applicability of the results
 - for a verification and an improvement of the model;
 - for a reliable prediction of the final output.
- Future plans
 - other approximation tools;
 - computations with 3D version of UNI-DEM;
 - studies of model sensitivity depending on emissions levels and boundary conditions.

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